pyCarla Release 0.1

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A python module for synthesizing MIDI events and files from python code using any kind of audio plugin!

A python module based on carla and jack!

ONE

INSTALLATION

The backbone of this project are the multiple dependencies on which it depends. Since it's difficult to provide a script to automatically install all of these dependencies, here is a little handbook about how to install them.

1.1 TLDR

- 1. Use Linux: it's free. For Windows and Mac, you can still install Carla and Jack by yourself; however, I refuse to support non-free software.
- 2. In general, use https://pkgs.org to look for the command needed in your distro.
- 3. Install: jackd 1.9
- 4. Make sure that it is available in your PATH environment variable

1.2 1. Installing pycarla

pip install --upgrade pip pycarla

1.3 2. Installing jack

- 1. Ubuntu/Debian based: sudo apt-get install jackd2
- 2. Arch based: sudo pacman -Sy jack2
- 3. Gentoo based: sudo emerge -a media-sound/jack2
- 4. Fedora based: sudo dnf install jack-audio-connection-kit

For other Os, pre-built binaries are available at https://jackaudio.org/downloads/

1.4 3. Installing Carla

After having installed the package, run python -m pycarla.carla --download to download the correct version of Carla.

If you're not in Linux, pre-built binaries for major OS available at https://github.com/falkTX/Carla/releases/latest

N.B. Configure Carla in ``patchbay`` mode (if you cannot use GUI, set ``ProcessMode=3`` into ``~/.con-fig/falkTX/Carla2.conf``)

TWO

DEVELOPMENT SETUP

- 1. Install poetry: curl -sSL https://raw.githubusercontent.com/python-poetry/poetry/master/
 get-poetry.py | python
- 2. Enter root directory of this project
- 3. poetry update
- 4. Put all the Carla configurations that you want to use in data/carla_proj Note that you can use the default ones, provided you have the same plugins available, otherwise you have to delete the default project files.

Used plugins are:

- Pianoteq
- SalamanderGrandPianoV3 uncompressed in ~/salamander/
- Calf Reverb
- 1. Run poetry run -m pycarla <a_midi_file.mid> to do a little test

THREE

USAGE

3.1 Carla presets

- 1. Configure Carla in ``patchbay`` mode (if you cannot use GUI, set ``ProcessMode=3`` into ``~/.config/falkTX/Carla2.conf``)
- 2. python -m pycarla.carla --run to launch Carla and prepare configurations

3.2 Initialization

```
from pycarla import Carla, MIDIPlayer, AudioRecorder, get_smf_duration
carla = Carla("carla_project.carxp", ['-R', '-d', 'alsa'], min_wait=4)
carla.start()
player = MIDIPlayer()
recorder = AudioRecorder()
# or
with MIDIPlayer() as player, AudioRecorder() as recorder:
    # [...]
    pass
```

3.3 Playing and recording one note

```
print("Playing and recording one note..")
duration = 2
pitch = 64
recorder.start(duration + FINAL_DECAY)
player.synthesize_midi_note(pitch, 64, duration, 0, sync=True)
recorder.wait()
audio = recorder.recorded
if not np.any(audio):
    print("Error, no sample != 0")
    carla.kill() # this kills both Carla and Jack
    # carla.kill_carla() # this kills Carla but not Jack
    sys.exit()
```

3.4 Playing and recording a full MIDI file

In future, there shold be a function that does this snippet for you

You can also use AudioRecorder and MIDIPlayer as context managers in a with block; in this case, skip the *close()* at the end:

```
with pycarla.AudioRecorder() as recorder, pycarla.MIDIPlayer() as player:
    # do your stuffs
    pass
```

3.5 Closing server

```
try:
    carla.kill()
except Exception as e:
    print("Processes already closed!")
```

FOUR

CLASSES AND FUNCTIONS

4.1 Carla

class pycarla.carla.**Carla**(*proj_path: str, server_options: List[str] = [], min_wait: float = 0, nogui: bool = True*)

__make_carla_popen(proj_path)

exists(ports=['Carla:events*', 'Carla:audio*'])
simply checks if the Carla process is running and ports are available

ports is a list of string name representing Jack ports; you can use '*', '?' etc.

Returns bool – running, false otherwise

Return type True if all ports in *ports* exist and the Carla process is

get_ports()

kill()

kill carla and wait for the server

kill_carla()

kill carla, but not the server

restart()

Restarts both the server and Carla!

restart_carla()

Only restarts Carla, not the Jack server!

start()

Start carla and Jack and wait self.min_wait seconds after a Carla instance is ready.

wait_exists()

Waits until a Carla instance is ready in Jack

pycarla.carla.download()

pycarla.carla.run_carla()

4.2 Jack Server

class pycarla.jackserver.JackServer(options)

kill()

Just calls *self.process.kill()* and reset this object

restart()

Wait for the duration of this ExternalProcess, then kill and restart. If the duration is not set, it doesn't return

start()

Starts the server if not already started

4.3 Playing MIDI

class pycarla.midiplayer.MIDIPlayer

MIDI_PORT = 'Carla'

activate()

Activate the MIDI player client and set the connections.

If the Carla instance is not found, this method rase a *RuntimeWarning*. To avoid it, use Carla.exists method. Note that Carla.start already does that!

clear()

clears the _messages list

Synthesize a list of messages

- 1. Connect the port of this jack client to Carla if not yet done
- 2. Send the list of messages to the Carla instance

If *sync* is True, this function waits until all messages have been processed, otherwise, it suddenly returns. You can wait by calling the *wait* method of this object.

This function is compatible with freewheeling mode. Freewheel prevents jack from waiting between return calls. This allows for the maximum allowed speed, but not output/input operation is done with system audio (i.e. you cannot listen/recording to anything while in freewheeling mode).

condition is a function checked in the playing callback. If *condition()* is False, no message is sent. The callback start playing at the cycle after the one in which *condition()* becomes True.

kwargs are passed to wait if sync is True.

Note: Mido numbers channels 0 to 15 instead of 1 to 16. This makes them easier to work with in Python but you may want to add and subtract 1 when communicating with the user.

synthesize_midi_file(*midifile: Any*, ***kwargs*) → multiprocessing.context.Process

Send midi messages contained in *filename* using *self.synthesize_messages*. All keywords from that method can be used here.

midifile can be a mido.MidiFile object or a string

After the playback, ports are resetted

synthesize_midi_note(*pitch: int, velocity: int, duration: float, sustain: int* = 0, *soft: int* = 0, *sostenuto: int* = 0, *channel: int* = 0, *program: int* = 0, **kwargs) \rightarrow

multiprocessing.context.Process

set up a list of messages representing one note and then calls *self.synthesize_messages*. All keywords from that method can be used here.

4.4 Recording Audio

class pycarla.audiorecorder.AudioRecorder

AUDIO_PORT = 'Carla'

activate()

Activate the recording client and set the connections. Set self.channels and create one input port per each Carla output port.

If the Carla instance is not found, this method rase a *RuntimeWarning*. To avoid it, use Carla.exists method. Note that Carla.start already does that!

clear()

Clears the recorded array

save_recorded(filename)

Save the recorded array to file. Extensions supported by libsndfile!

start_frame is the frame from which recorded is saved (use it to discard initial delays due to Jack setup).

start(*duration=None*, *sync=False*, *condition=<function AudioRecorder.<lambda>>*, **kwargs)

Record audio for duration seconds. Note that this function blocks if *sync* is True, otherwise, this returns suddenly and you should wait/stop by calling the *wait* method of this object which constructs the recorded array in *self.recorded*

condition is a function checked in the recording callback. If *condition()* is False, blocks are discarded. The callback start recording at the cycle after the one in which *condition()* becomes True.

This function is compatible with Jack freewheeling mode to record offline sessions.

kwargs are passed to wait if sync is True.

wait(timeout=None, in_fw=False, out_fw=False)

Wait until recording is finished. If *timeout* is a number, it should be the maximum number of seconds until which the recording stops. A boolean is returned representing if timeout is reached. (returns *False* if timeout is not set)

The recording stops when *timeout* or the duration passed when calling *start* is reached. In these cases, the recording client is deactivated and the callback stopped.

waits while setting freewheeling mode to *in_fw* it then set freewheeling mode to *out_fw* before exiting

WHY SO MANY EXTERNAL DEPENDENCIES?

Python has no strong real-time capabilities since it cannot run with parallel threads. This method delegates most of the realtime stuffs to external C/C++ programs, improving the performances and the accuracy against pure-Python based approaches. Namely, the synthesis and the management of plugins is delegated to Carla, while the MIDI messaging and audio recording is done in python using C Jack API.

This method is really portable and supports almost any type of plugins and virtual instruments thanks to the excellent Carla:

- 1. Linux VST2/VST3
- 2. Windows VST2/VST3
- 3. LV2
- 4. LADSPA
- 5. DSSI
- 6. AU
- 7. SF2/SF3
- 8. SFZ
- 9. Any other format supported by external plugins

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CREDITS

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