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**pyCarla**

***Release 0.1***

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A python module for synthesizing MIDI events and files from python code using any kind of audio plugin!

A python module based on carla and jack!



## INSTALLATION

The backbone of this project are the multiple dependencies on which it depends. Since it's difficult to provide a script to automatically install all of these dependencies, here is a little handbook about how to install them.

### 1.1 TLDR

1. Use Linux: it's free. For Windows and Mac, you can still install Carla and Jack by yourself; however, I refuse to support non-free software.
2. In general, use <https://pkgs.org> to look for the command needed in your distro.
3. Install: `jackd 1.9`
4. Make sure that it is available in your `PATH` environment variable

### 1.2 1. Installing pycarla

```
pip install --upgrade pip pycarla
```

### 1.3 2. Installing jack

1. Ubuntu/Debian based: `sudo apt-get install jackd2`
2. Arch based: `sudo pacman -Sy jack2`
3. Gentoo based: `sudo emerge -a media-sound/jack2`
4. Fedora based: `sudo dnf install jack-audio-connection-kit`

For other Os, pre-built binaries are available at <https://jackaudio.org/downloads/>

## 1.4 3. Installing Carla

After having installed the package, run `python -m pycarla.carla --download` to download the correct version of Carla.

If you're not in Linux, pre-built binaries for major OS available at <https://github.com/falkTX/Carla/releases/latest>

**N.B. Configure Carla in `patchbay` mode (if you cannot use GUI, set `ProcessMode=3` into `~/.config/falkTX/Carla2.conf`)**

To set patchbay mode in the GUI: *settings -> Engine -> Process mode -> Patchbay -> Ok*



## DEVELOPMENT SETUP

The next steps are only needed for contributing to this project. Do not follow them if you only want to use `pycarla`

1. Install poetry: `curl -sSL https://raw.githubusercontent.com/python-poetry/poetry/master/get-poetry.py | python`
2. Enter root directory of this project
3. `poetry update`
4. Put all the Carla configurations that you want to use in `data/carla_proj` Note that you can use the default ones, provided you have the same plugins available, otherwise you have to delete the default project files.

**Tested plugins are:**

- Pianoteq
- [SalamanderGrandPianoV3](#)
- Calf Reverb

1. Run `poetry run python -m pycarla <a_midi_file.mid>` to do a little test



## 3.1 Carla presets

1. Configure Carla in ``patchbay`` mode (if you cannot use GUI, set ``ProcessMode=3`` into ``~/config/falkTX/Carla2.conf``)
2. `python -m pycarla.carla --run` to launch Carla and prepare configurations

## 3.2 Initialization

```
from pycarla import Carla, MIDIPlayer, AudioRecorder, get_smf_duration
carla = Carla("carla_project.carxp", ['-R', '-d', 'alsa'], min_wait=4)
carla.start()

player = MIDIPlayer()
recorder = AudioRecorder()

# or
with MIDIPlayer() as player, AudioRecorder() as recorder:
    # [...]
    pass
```

## 3.3 Playing and recording one note

```
print("Playing and recording one note..")
duration = 2
pitch = 64
recorder.start(duration + FINAL_DECAY)
player.synthesize_midi_note(pitch, 64, duration, 0, sync=True)
recorder.wait()
audio = recorder.recorded
if not np.any(audio):
    print("Error, no sample != 0")
    carla.kill() # this kills both Carla and Jack
    # carla.kill_carla() # this kills Carla but not Jack
    sys.exit()
```

## 3.4 Playing and recording a full MIDI file

```
print("Playing and recording full file using freewheeling mode..")
duration = get_smf_duration("filename.mid")
# in the following, `condition` ensures that both the recorder and player
# start in the same cycle
recorder.start(duration + FINAL_DECAY, condition=player.is_ready)
player.synthesize_midi_file("filename.mid",
    condition=recorder.is_ready, in_fw=True, out_fw=True)
# or asynchronously:
# player.synthesize_midi_file("filename.mid", sync=False)
# in this case, use
# player.wait(in_fw=True, out_fw=True)
recorder.wait(in_fw=True, out_fw=True)
recorder.save_recorded("session.wav")
player.close()
server.close()
```

In future, there should be a function that does this snippet for you

You can also use `AudioRecorder` and `MIDIPlayer` as context managers in a `with` block; in this case, skip the `close()` at the end:

```
with pycarla.AudioRecorder() as recorder, pycarla.MIDIPlayer() as player:
    # do your stuffs
    pass
```

## 3.5 Closing server

```
try:
    carla.kill()
except Exception as e:
    print("Processes already closed!")
```

## CLASSES AND FUNCTIONS

### 4.1 Carla

```
class pycarla.carla.Carla(proj_path: str, server_options: List[str] = [], min_wait: float = 0, nogui: bool = True)
```

```
    __make_carla_popen(proj_path)
```

```
    exists(ports=['Carla:events*', 'Carla:audio*'])
```

simply checks if the Carla process is running and ports are available

**ports is a list of string name representing Jack ports; you can use**  
 **'\*', '?'** etc.

**Returns**

**bool** – running, false otherwise

**Return type**

True if all ports in *ports* exist and the Carla process is

```
    get_ports()
```

```
    kill()
```

kill carla and wait for the server

```
    kill_carla()
```

kill carla, but not the server

```
    restart()
```

Restarts both the server and Carla!

```
    restart_carla()
```

Only restarts Carla, not the Jack server!

```
    start()
```

Start carla and Jack and wait *self.min\_wait* seconds after a Carla instance is ready.

```
    wait_exists()
```

Waits until a Carla instance is ready in Jack

```
pycarla.carla.download()
```

```
pycarla.carla.is_within_directory(directory, target)
```

```
pycarla.carla.run_carla()
```

```
pycarla.carla.safe_extract(tar, path='.', members=None, *, numeric_owner=False)
```

## 4.2 Jack Server

```
class pycarla.jackserver.JackServer(options)
```

```
    kill()
```

Just calls *self.process.kill()* and reset this object

```
    restart()
```

Wait for the duration of this *ExternalProcess*, then kill and restart. If the duration is not set, it doesn't return

```
    start()
```

Starts the server if not already started

## 4.3 Playing MIDI

```
class pycarla.midiplayer.MIDIPlayer
```

```
    MIDI_PORT = 'Carla'
```

```
    activate()
```

Activate the MIDI player client and set the connections.

If the Carla instance is not found, this method raise a *RuntimeWarning*. To avoid it, use *Carla.exists* method. Note that *Carla.start* already does that!

```
    clear()
```

clears the *\_messages* list

```
    synthesize_messages(messages: ~typing.List[mido.Message], sync=False, condition=<function  
                           MIDIPlayer.<lambda>>, **kwargs)
```

Synthesize a list of messages

1. Connect the port of this jack client to Carla if not yet done
2. Send the list of messages to the Carla instance

If *sync* is True, this function waits until all messages have been processed, otherwise, it suddenly returns. You can wait by calling the *wait* method of this object.

This function is compatible with freewheeling mode. Freewheel prevents jack from waiting between return calls. This allows for the maximum allowed speed, but not output/input operation is done with system audio (i.e. you cannot listen/recording to anything while in freewheeling mode).

*condition* is a function checked in the playing callback. If *condition()* is False, no message is sent. The callback start playing at the cycle after the one in which *condition()* becomes True.

*kwargs* are passed to *wait* if *sync* is True.

Note: Mido numbers channels 0 to 15 instead of 1 to 16. This makes them easier to work with in Python but you may want to add and subtract 1 when communicating with the user.

**synthesize\_midi\_file**(*midifile: Any, \*\*kwargs*) → Process

Send midi messages contained in *filename* using *self.synthesize\_messages*. All keywords from that method can be used here.

*midifile* can be a *mido.MidiFile* object or a string

After the playback, ports are resetted

**synthesize\_midi\_note**(*pitch: int, velocity: int, duration: float, sustain: int = 0, soft: int = 0, sostenuto: int = 0, channel: int = 0, program: int = 0, \*\*kwargs*) → Process

set up a list of messages representing one note and then calls *self.synthesize\_messages*. All keywords from that method can be used here.

## 4.4 Recording Audio

**class** pycarla.audiorecorder.**AudioRecorder**

**AUDIO\_PORT** = 'Carla'

**activate**()

Activate the recording client and set the connections. Set *self.channels* and create one input port per each Carla output port.

If the Carla instance is not found, this method raise a *RuntimeWarning*. To avoid it, use *Carla.exists* method. Note that *Carla.start* already does that!

**clear**()

Clears the *recorded* array

**save\_recorded**(*filename*)

Save the recorded array to file. Extensions supported by *libsndfile*!

*start\_frame* is the frame from which recorded is saved (use it to discard initial delays due to Jack setup).

**start**(*duration=None, sync=False, condition=<function AudioRecorder.<lambda>>, \*\*kwargs*)

Record audio for *duration* seconds. Note that this function blocks if *sync* is True, otherwise, this returns suddenly and you should wait/stop by calling the *wait* method of this object which constructs the recorded array in *self.recorded*

*condition* is a function checked in the recording callback. If *condition()* is False, blocks are discarded. The callback start recording at the cycle after the one in which *condition()* becomes True.

This function is compatible with Jack freewheeling mode to record offline sessions.

*kwargs* are passed to *wait* if *sync* is True.

**wait**(*timeout=None, in\_fw=False, out\_fw=False*)

Wait until recording is finished. If *timeout* is a number, it should be the maximum number of seconds until which the recording stops. A boolean is returned representing if timeout is reached. (returns *False* if timeout is not set)

The recording stops when *timeout* or the duration passed when calling *start* is reached. In these cases, the recording client is deactivated and the callback stopped.

waits while setting freewheeling mode to *in\_fw* it then set freewheeling mode to *out\_fw* before exiting





## **WHY SO MANY EXTERNAL DEPENDENCIES?**

Python has no strong real-time capabilities since it cannot run with parallel threads. This method delegates most of the realtime stuffs to external C/C++ programs, improving the performances and the accuracy against pure-Python based approaches. Namely, the synthesis and the management of plugins is delegated to Carla, while the MIDI messaging and audio recording is done in python using C Jack API.

This method is really portable and supports almost any type of plugins and virtual instruments thanks to the excellent Carla:

1. Linux VST2/VST3
2. Windows VST2/VST3
3. LV2
4. LADSPA
5. DSSI
6. AU
7. SF2/SF3
8. SFZ
9. Any other format supported by external plugins



CREDITS

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